

Servo amplifier

mcDSA-E25XC-EtherCAT

Article number: 1513850

 Certification: 

E475093


Picture similar

Technical data

Absolute maximum rating (destruction limits)	
Power supply voltage Up no polarity reversal protection	80 V
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V
Short term peak voltage < 1s Ue no polarity reversal protection	37 V
Power	
Electronic supply voltage Ue	9..30 V
Electronic current consumption@ Ue=24V*2	typ. 100 mA
Power supply voltage Up	9..60 V
Max. output current	160 A
Continuous output current (certified UL/CE)*3 @Up=24V	54 A
@Up=60V	49 A
Continuous output current (not certified)*4 @Up=24V	65 A
with Heatsink (Art.No. 1511832)	70 A
Continuous output current (not certified)*4 @Up=48V	55 A
with Heatsink (Art.No. 1511832)	65 A
PWM	
Output voltage	100% Up
PWM frequency	25, 32*5, 50 kHz
Mechanical	
Size LxWxH	111.1 x 100 x 55.4 mm
Weight	630 g
Environment	
Protection class	IP20
Ambient temperature (operation) (certified UL/CE)	-25..40 °C
Ambient temperature (operation) (not certified)	-25..70 °C
Ambient temperature (storage)	-25..85 °C
Rel. humidity (non-condensing)	5..90 %
CAN bus	
Protocol	DS301
Device profile	DS402
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	yes
EtherCAT	
Type	EtherCAT Slave
Physical layer	100 Base-Tx EtherCAT
Bus controller	ET1100
Max. baudrate	100 Mbit/s
Number of ports	2xRJ45 (In,Out)
Protocol	CoE (CANopen over EtherCAT)

*1 The certified performance data must be observed (see UL Instruction Note and Safety Manual (CE))

*2 power amplifier switched off, 5V output (sensor supply) is free, STO active

*3 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (asymmetrical), ambient temperature 40 °C, I/O's and 5V output active, RMS current: 54 A → 44 Aeff, 49 A → 40 Aeff

*4 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (asymmetrical), ambient temperature 40 °C, I/O's and 5V output free, RMS current: 55 A → 45 Aeff, 65 A → 53 Aeff, 70 A → 57 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

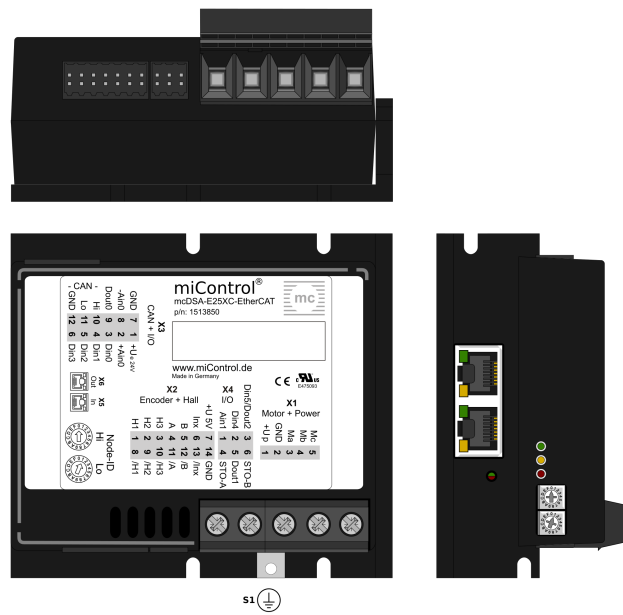
*5 default value

*6 Input voltage must not exceed Electronic supply voltage Ue

Additional technical data are available in mcManual.

Functional safety	
Safety function refer safety manual	Safe Torque Off (STO)
Safety Integrity Level (SIL)	up to SIL 3
Performance Level (PL)	up to PL e
Sensor supply (Encoder/Hall)	
Output voltage	5 V
Max. output current	0.2 A
Incremental encoder	
Type	incremental
Signals	A,/A,B,/B,Inx,/Inx
Max. frequency (per channel)	500 kHz
Input voltage (24V tolerant)	0..5 V
Signal type	differential, open collector, single ended
Hall sensors	
Signals	H1,/H1,H2,/H2,H3,/H3
Max. frequency (per channel)	10 kHz
Input voltage (24V tolerant)	0..5 V
Signal type	differential, open collector, single ended
Digital inputs	
Number - digital inputs	6 (Din0..5)
Low voltage	0..5 V
High voltage	8..30 V
Notice	Din5 parallel with Dout2*6
STO channels (ST0-A..B)	
Low voltage	0..5 V
High voltage	8..30 V
Digital outputs	
Number	3 (Dout0..2)
Continuous output current (certified UL/CE)	1 A
Continuous output current (not certified)	1.5 A
Load	resistive, inductive
Output voltage	Electronic supply voltage Ue
Signal type	positive switching
Notice	Dout2 parallel with Din5
Analog inputs	
Number	2 (Ain0..1)
Signal type - Ain0	+/- 10 V, 12 Bit, differential
Signal type - Ain1	+/- 10 V, 12 Bit, single ended

Scheme



S1

© 2021 by miControl

Terminal assignment

X1 Motor		
1	+Up	Power supply voltage
2	GND	Ground for power supply voltage
3	Ma	Motor phase A
4	Mb	Motor phase B
5	Mc	Motor phase C
X2 Hall and inc. encoder		
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	A	Inc. encoder, A channel
5	B	Inc. encoder, B channel
6	Inx	Inc. encoder, index channel
7	+U5V	5V output voltage for sensor supply Sensors: encoder, hall
8	/H1	Hall sensor 1 inverted
9	/H2	Hall sensor 2 inverted
10	/H3	Hall sensor 3 inverted
11	/A	Inc. encoder, A channel inverted
12	/B	Inc. encoder, B channel inverted
13	/Inx	Inc. encoder, index channel inverted
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3 I/O's and CAN		
1	+Ue24V	Electronic supply voltage
2	+Ain0	Analog input 0, plus
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	-Ain0	Analog input 0, minus
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground

X4 I/O's		
1	Ain1	Analog input 1
2	Din4	Digital input 4
3	Din5/Dout2	Digital input 5 / Digital output 2
4	STO-A	STO channel A
5	Dout1	Digital output 1
6	STO-B	STO channel B
S1 Screw (M4)		
-	FE	Functional earth
X5 EtherCAT - In port		
-	In	In
X6 EtherCAT - Out port		
-	Out	Out